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Design of a Segmented LGAD Sensor for Development of 4-D Tracking Detector





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4D Tracker



Tracks reconstructed by ATLAS (event with 17 interactions) ➡ Expect 200/crossing at HL-LHC



- Identify vertices otherwise difficult using position information only
- Effective in forward regions where vertexing precision is limited

 $(\Delta t=10ps \rightleftharpoons \Delta z=3mm)$

collision points Position

Time



Low-Gain Avalanche Detector (LGAD)

Add p⁺ layer underneath the n⁺ readout electrode High E-field induces avalanche multiplication

- ▶ thin (50µm) substrate is effective for signal creation
- short charge collection time with fast signal shape
 - \rightarrow good time resolution O(10ps)



Strip type

strip pitch : 80µm

90

HPK LGAD samples





- Should we add time information to each hit,
- Reconstruct tracks using proper time differences
- Help reduce wrong hit combinations and effective in reducing the track reconstruction CPU
 - \rightarrow Innovation in tracking



Pad type

window : 1mmD

Active thickness : 50 or 80µm (150µm physical) p⁺ layer concentration : 4 steps (A<B<C<D)

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Signal readout

LGAD signal is amplified (using high-speed amps) and digitized using DRS4 flash ADCs (5GS/s)

Pulse height : 12bit, 1Vpp $(1V/4096 \sim 0.25mV)$ ▶ Time bins : 10bit, 5GS/s (200ps*1024~200ns F.S.)



 $V_{thresh} = f \times V_{peak}$







TCAD Simulation for Segmented LGADs

TCAD Sentaurus[™] (synopsys)



Summary

We are developing LGAD sensors to realise 4-D tracking detector

- Time precision better than 30 ps is obtained from test beam measurements
- ➡ TCAD simulation tuned to reproduce measured characteristics is used to design segmented LGAD sensors. Trench is a good candidate. Continue to optimize the electrode structure and trench process



